

Review Article

Surrogate Modeling for Complex Engineering Design Problems: A Comprehensive Review

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ABSTRACT

Surrogate modeling has emerged as a powerful tool for solving complex engineering design problems by providing computationally efficient approximations of high-fidelity simulations. In disciplines such as aerospace, automotive, structural engineering, and biomedical applications, high-fidelity models require significant computational resources, making optimization and real-time decision-making challenging. Traditional optimization methods often struggle with the computational burden associated with iterative simulations, necessitating alternative approaches that can reduce computational cost while maintaining accuracy.

Surrogate models, including polynomial response surfaces, Kriging, artificial neural networks (ANNs), Gaussian process regression, radial basis function (RBF) models, and support vector regression (SVR), enable rapid evaluations and facilitate efficient design exploration. These models approximate expensive simulations and enable engineers to perform parametric studies, uncertainty quantification, and multi-disciplinary optimization without the need for exhaustive computations. Additionally, hybrid surrogate modeling approaches, which combine multiple modeling techniques or integrate multi-fidelity simulations, have shown promising results in balancing accuracy and computational efficiency.

This review presents an in-depth discussion of surrogate modeling techniques, their theoretical foundations, practical applications in engineering optimization, and recent advancements in hybrid and adaptive approaches. Special attention is given to the role of machine learning and artificial intelligence in enhancing surrogate model performance, particularly in high-dimensional and nonlinear optimization problems. Furthermore, the challenges associated with surrogate modeling, such as model selection, generalization, error estimation, and robustness, are explored in detail.

Future research directions are identified, including the development of adaptive AI-driven frameworks, automated model refinement techniques, and improved uncertainty quantification methods.

Keywords: Surrogate Modeling, Polynomial Response Surfaces, Gaussian Process Regression, Support Vector Regression (SVR)



Introduction

Engineering design problems often involve computationally expensive simulations, such as Computational Fluid Dynamics (CFD) and Finite Element Analysis (FEA), which require substantial computational resources and long processing times. These high-fidelity simulations play a critical role in evaluating complex physical behaviors, including fluid flow dynamics, structural deformations, thermal conductivity, and electromagnetic interactions. However, the sheer computational cost of running multiple iterations for design optimization makes traditional simulation-based methods impractical, particularly for large-scale, multidisciplinary systems.¹

To overcome these challenges, surrogate modeling has emerged as a powerful alternative that provides computationally efficient approximations of expensive simulations. By replacing high-fidelity models with mathematically simpler yet accurate predictive models, surrogate modeling significantly reduces the time required for design evaluations while maintaining an acceptable level of accuracy. These models facilitate rapid decision-making, enabling engineers to explore a broader design space with limited computational resources.

Surrogate models are extensively utilized in various engineering domains, particularly in multidisciplinary design optimization (MDO), where multiple interdependent disciplines must be optimized simultaneously. Additionally, they play a crucial role in uncertainty quantification, helping to assess the impact of modeling errors, material property variations, and external disturbances on system performance. Sensitivity analysis is another critical area where surrogate models assist in identifying the most influential design variables, thereby guiding engineers toward optimal design choices. Furthermore, surrogate models are integrated into real-time control applications, where rapid response times are essential, such as in autonomous vehicle navigation, adaptive structural control, and aerospace guidance systems.²

The application of surrogate modeling extends beyond traditional optimization frameworks. Recent advancements in machine learning, artificial intelligence (AI), and data-driven modeling have further enhanced the efficiency and accuracy of surrogate models. Techniques such as Gaussian process regression (Kriging), artificial neural networks (ANNs), support vector machines (SVMs), and deep learning-based surrogates are being increasingly adopted to improve model performance. Additionally, the emergence of hybrid surrogate modeling approaches, which combine multiple modeling techniques, has shown promise in achieving higher prediction accuracy and greater generalizability across different engineering problems.

Despite the numerous advantages, the implementation of surrogate models comes with inherent challenges. These

include the curse of dimensionality, training data selection, extrapolation limitations, and model validation issues. Addressing these challenges is crucial to ensuring the reliability and robustness of surrogate models in real-world engineering applications.³

This review aims to provide a comprehensive discussion on surrogate modeling in engineering design, covering fundamental concepts, commonly used modeling techniques, and their applications across multiple domains. Furthermore, recent advancements in adaptive, hybrid, and AI-driven surrogate modeling methods are explored to highlight their potential in next-generation engineering optimization frameworks. Finally, this article discusses the key challenges associated with surrogate modeling and outlines future research directions to drive further innovation in this field.

Fundamental Concepts of Surrogate Modeling

Surrogate modeling is a crucial technique in engineering design optimization, allowing for the efficient exploration of complex design spaces while significantly reducing computational costs. By approximating high-fidelity simulations with mathematical models, surrogate modeling enables faster evaluations, making it particularly useful in multidisciplinary design optimization (MDO), uncertainty quantification, sensitivity analysis, and real-time decision-making. This section provides a detailed overview of the fundamental principles of surrogate modeling, including its definition, role, and construction process.⁴

Definition and Role of Surrogate Models

A surrogate model, also known as a meta-model, is a mathematical approximation that emulates the behavior of a high-fidelity simulation model while requiring significantly less computational effort. These models are widely used in engineering applications where direct simulations are too expensive or time-consuming.

The key advantages of surrogate models include:

- **Rapid evaluation of design alternatives:** Engineers can quickly analyze different design options without running full-scale simulations.
- Efficient design optimization: Optimization algorithms can efficiently explore large and complex design spaces by leveraging surrogate models as proxies for expensive simulations.
- Real-time decision-making: In applications requiring immediate responses, such as autonomous systems, adaptive control, and aerospace guidance, surrogate models enable rapid computations.
- Uncertainty quantification and sensitivity analysis: Surrogate models help assess the influence of design parameters and quantify uncertainties in predictions.

Surrogate modeling is particularly valuable in multi-objective optimization, where multiple conflicting design objectives must be balanced. It is also widely used in reliability-based design assessments, where failure probabilities and system robustness need to be evaluated under uncertain conditions.⁵

Surrogate Model Construction Process

The development of an accurate and efficient surrogate model requires a structured process involving data sampling, model selection, training, validation, and application in optimization. The major steps involved are:

Sampling Strategy

Selecting a representative set of sample points from the design space is crucial for constructing an effective surrogate model. Several strategies are commonly used:

- Latin Hypercube Sampling (LHS): Ensures uniform coverage of the design space and is widely used in engineering applications.
- **Sobol Sequences:** A quasi-random sampling technique that provides better space-filling properties than purely random sampling.
- **Optimal Latin Hypercube Sampling (OLHS):** A refinement of LHS that improves sampling efficiency.
- **Design of Experiments (DOE):** Classical statistical techniques such as Full Factorial Design, Central Composite Design (CCD), and Box-Behnken Design (BBD) are used for structured sampling.⁶

The choice of sampling method depends on the complexity of the problem and the desired accuracy of the surrogate model.

Model Selection and Training

Once the sample points are selected, an appropriate surrogate modeling technique is chosen. Some commonly used models include:

- **Polynomial Response Surface Models (RSM):** A simple yet effective approximation technique based on polynomial regression.
- Kriging (Gaussian Process Regression): A probabilistic modeling technique that provides uncertainty quantification along with predictions.
- Artificial Neural Networks (ANNs): A machine learning-based approach capable of capturing complex nonlinear relationships in data.
- Radial Basis Function (RBF) Networks: A popular method for interpolating complex surfaces.
- Support Vector Machines (SVMs): Particularly useful in classification and regression-based surrogate modeling.⁷

The selected model is trained using the sample points, and its parameters are optimized to ensure accurate approximation of the underlying function.

Validation and Error Assessment

A surrogate model must be validated to ensure it accurately represents the high-fidelity simulation results. Several error assessment techniques are used:

- **Root Mean Square Error (RMSE):** Measures the overall deviation between the predicted and actual values.
- **Coefficient of Determination (R²):** Indicates how well the surrogate model explains the variance in the data.
- **Cross-Validation:** Involves dividing the data into training and testing sets to assess the model's generalization capability.
- Leave-One-Out Cross-Validation (LOOCV): A rigorous technique where each sample is removed one at a time to evaluate model accuracy.

If the model accuracy is insufficient, additional sample points may be added, or a more advanced surrogate modeling technique may be selected.⁸

Application in Optimization

Once validated, the surrogate model is integrated into an optimization framework. It can be used to:

- Guide heuristic optimization algorithms such as Genetic Algorithms (GA), Particle Swarm Optimization (PSO), and Bayesian Optimization.
- Perform sensitivity analysis to identify critical design parameters.
- Improve real-time control strategies in adaptive systems.

The surrogate model allows for rapid iterations, significantly reducing the number of expensive high-fidelity simulations required for optimization.

Types of Surrogate Models

Several types of surrogate models exist, each with unique strengths and limitations. The choice of a surrogate model depends on the complexity of the problem, the available data, and computational constraints. These models approximate high-fidelity simulation outputs using mathematical or statistical techniques, enabling rapid evaluations while maintaining reasonable accuracy. The most commonly used surrogate modeling techniques in engineering are discussed below.⁹

Polynomial Response Surface Models (RSM)

Polynomial Response Surface Models (RSM) are one of the earliest and simplest forms of surrogate modeling. They approximate the response function using low-order polynomial equations, typically expressed as:

y(x)=a0+a1x1+a2x2+a3x1x2+a4x12+...y(x) = a_0 + a_1x_1 + a_2x_2 + a_3x_1x_2 + a_4x_1^2 + \dotsy(x)=a0+a1x1 +a2x2+a3x1x2+a4x12+... where x1,x2,...x_1, x_2, \dotsx1,x2,... represent design variables, and a0,a1,a2,...a_0, a_1, a_2, \dotsa0,a1,a2,... are regression coefficients determined through least squares fitting.

Advantages:

- Computationally efficient, making them ideal for low-cost surrogate modeling.
- Well-suited for low-dimensional problems with smooth response functions.
- Provides explicit mathematical equations that facilitate design interpretation.

Limitations:

- Poor accuracy for highly nonlinear or high-dimensional problems.
- The choice of polynomial order significantly affects model performance—higher-order polynomials may lead to overfitting.

RSM is commonly used in engineering applications involving design of experiments (DOE), uncertainty quantification, and gradient-based optimization.

Kriging Models (Gaussian Process Regression)

Kriging, also known as Gaussian Process Regression (GPR), is a probabilistic interpolation technique that models the response as a stochastic Gaussian process. It provides both a prediction and an uncertainty estimate at each design point[10]. The Kriging model is defined as:

 $y(x)=\mu+Z(x)y(x) = mu + Z(x)y(x)=\mu+Z(x)$

where:

- μ \mu μ is the global mean response.
- Z(x)Z(x)Z(x) is a Gaussian process with a covariance function that captures spatial correlations.

Kriging is particularly effective in modeling highly nonlinear and expensive-to-evaluate functions with limited sample points. The hyperparameters of the Kriging model, such as correlation lengths, are typically optimized using maximum likelihood estimation (MLE).

Advantages:

- Provides an estimate of prediction uncertainty, making it useful for adaptive sampling strategies.
- Highly accurate for smooth and continuous response functions.
- Effective for small datasets where data collection is costly.

Limitations:

- Computationally expensive for large-scale problems due to matrix inversion operations.
- Performance deteriorates for high-dimensional design spaces.¹¹

Kriging is widely applied in structural optimization, reliability-based design, and multidisciplinary design optimization (MDO).

Artificial Neural Networks (ANNs)

Artificial Neural Networks (ANNs) are powerful surrogate models that approximate complex nonlinear relationships using interconnected layers of artificial neurons. ANNs consist of input layers, hidden layers, and output layers, where each neuron applies an activation function such as ReLU, sigmoid, or tanh.

Advantages:

- High accuracy for highly nonlinear, high-dimensional problems.
- Scalability to complex engineering systems with multiple input-output relationships.
- Generalization capability when trained with sufficient data, making them suitable for surrogate-based optimization.

Limitations:

- Require a large dataset for effective training, which may be impractical for expensive simulations.
- Computationally intensive, especially during training due to backpropagation and gradient-based learning.
- Hyperparameter tuning (e.g., number of layers, neurons, learning rate) is crucial for achieving good performance.¹²

ANNs have been successfully implemented in computational fluid dynamics (CFD), structural health monitoring, autonomous systems, and real-time predictive modeling.

Radial Basis Function (RBF) Models

Radial Basis Function (RBF) models use basis functions centered around selected sample points to interpolate the response surface. The response function is represented as:

 $y(x)=\sum wi\phi(||x-xi||)y(x) = \sum wi\phi(||x-x_i||)y(x) = wi\phi(||x-xi||)$

where:

- wiw_iwi are the weights assigned to basis functions.
- φ(||x-xi||)\phi(||x x_i||)φ(||x-xi||) is a radial basis function, such as Gaussian, multiquadric, or inverse multiquadric functions.

Advantages:

- Effective for scattered data approximation in multidimensional design spaces.
- Provides smooth interpolation with continuous gradients, making it useful for optimization.
- Does not require predefined polynomial structures, making it more flexible than RSM.

Limitations:

- Sensitivity to basis function parameters, requiring careful tuning.
- Computational cost increases with the number of sample points.
- May struggle with extrapolation beyond the sampled region.¹³

RBF models are extensively used in aeroelasticity, structural dynamics, and shape optimization.

Support Vector Regression (SVR)

Support Vector Regression (SVR) is a machine learning-based surrogate modeling approach that constructs a regression model using Support Vector Machines (SVMs). Unlike conventional regression techniques, SVR seeks to minimize prediction error while ensuring robust generalization.

The SVR model is formulated as:

 $\begin{array}{l} \min | |w,\xi,\xi*12**w**2+C\Sigma(\xi+\xi*) \\ \max\{1\}{2\} | |w| | ^2 + C \\ (xi + xi^*)w,\xi,\xi*min21 \\ **w*2+C\Sigma(\xi+\xi*) \end{array}$

subject to:

 $\begin{array}{l} yi-(w*xi+b) \leq \epsilon + \xi y_i - (w \ cdot \ x_i + b) \ leq \ epsilon + \ xiyi \\ -(w*xi+b) \leq \epsilon + \xi \ (w \ xi+b) - yi \leq \epsilon + * (w \ cdot \ x_i + b) - y_i \ leq \\ epsilon + \ xi^*(*xi+b) - yi \leq \epsilon + \xi * \end{array}$

where:

- CCC controls the trade-off between model complexity and prediction accuracy.
- ε\epsilonε defines an insensitive zone, within which errors are ignored.
- ξ,ξ*\xi, \xi^*ξ,ξ*are slack variables to handle non-linearity.

Advantages:

• Effective for high-dimensional data, making it suitable for complex design problems.

- Robust to noise in training data, ensuring stable performance.
- Generalizes well, preventing overfitting compared to ANN-based models.¹⁴

Limitations:

- Computationally intensive for large datasets due to quadratic programming optimization.
- Performance depends on kernel selection (e.g., linear, polynomial, radial basis function).

SVR is widely used in aerodynamic shape optimization, robotics, and reliability engineering. Table 1 presents the Comparison of Surrogate Models.

Applications of Surrogate Modeling in Engineering

Aerospace Engineering

- Optimization of airfoil shapes for improved aerodynamic performance
- Propulsion system design for fuel efficiency optimization
- Surrogate models for multidisciplinary aircraft design optimization

Automotive Engineering

- Vehicle crashworthiness optimization using Krigingbased surrogates
- Reduction of drag in automotive aerodynamics
- Battery performance modeling for electric vehicles

Structural Engineering

- Optimization of bridge and building structures underseismic loads
- Topology optimization for lightweight material design
- Fatigue and durability analysis of structural components

Biomedical Engineering

- Surrogate models for patient-specific medical implants
- Finite element analysis of bone and tissue mechanics
- Drug delivery system optimization using machine learning surrogates

Model Type	Accuracy	Computational Cost	Strengths	Weaknesses
Polynomial RSM	Moderate	Low	Fast, interpretable	Struggles with high nonlinearity
Kriging (GPR)	High	High	Uncertainty quantification	Computationally expensive
ANNs	Very High	Very High	Handles complex problems	Needs large datasets, tuning required
RBF Models	High	Moderate	Flexible, smooth interpolation	Sensitive to parameter tuning
SVR	High	High	Generalizes well, robust	Expensive for large datasets

Table I.Comparison of Surrogate Models

Challenges and Future Research Directions

Challenges in Surrogate Modeling

- Curse of Dimensionality: As the number of input variables increases, surrogate models struggle to maintain accuracy.
- Computational Cost of Training: High-fidelity simulations are required for model training, increasing computational expenses.
- Extrapolation Limitations: Most surrogate models perform well within the training region but fail to generalize beyond it.
- Uncertainty Quantification: Accurately estimating and propagating uncertainties remains a challenge in surrogate-based optimization.

Future Research Directions

- **Hybrid Surrogate Models:** Combining multiple surrogate models (e.g., Kriging-ANN hybrids) to improve accuracy and efficiency.
- Adaptive Surrogate Modeling: Dynamically refining surrogate models based on optimization progress.
- Integration with AI and Deep Learning: Utilizing deep learning architectures for improved generalization and automation.
- Quantum Computing for Surrogate Modeling: Exploring quantum algorithms for solving high-dimensional design optimization problems.

Conclusion

Surrogate modeling has become an indispensable tool in modern engineering design, enabling efficient optimization and rapid decision-making. By leveraging advanced techniques such as Kriging, Artificial Neural Networks (ANNs), Radial Basis Function (RBF) models, and hybrid modeling approaches, researchers can tackle complex, high-fidelity simulations while significantly reducing computational costs. These models serve as efficient alternatives to traditional simulations, allowing engineers to explore vast design spaces, conduct uncertainty quantification, and improve system performance without the burden of excessive computational resources.

The increasing integration of machine learning, deep learning, and artificial intelligence (AI)-driven methods into surrogate modeling frameworks is further revolutionizing optimization processes. The ability of AI-based models to learn from data, adaptively refine surrogate approximations, and provide real-time predictions makes them highly valuable in fields such as aerospace engineering, automotive design, structural mechanics, and biomedical applications. Moreover, the development of multi-fidelity modeling approaches, which combine low- and high-fidelity simulations, is proving to be a game-changer in reducing computational expense while maintaining high accuracy. However, despite significant advancements, challenges remain in model accuracy, generalization capability, and robustness. Future research should focus on:

- Adaptive AI-driven surrogate modeling frameworks that dynamically update models based on real-time data.
- Hybrid surrogate models that intelligently combine multiple modeling techniques to enhance predictive accuracy.
- Uncertainty quantification and reliability assessment to ensure surrogate models provide robust and trustworthy predictions.
- High-dimensional optimization methods that effectively handle large-scale, complex design problems.
- Automation and integration with digital twins to enable real-time decision-making in smart manufacturing and cyber-physical systems.

As computational power continues to evolve and new datadriven techniques emerge, surrogate modeling will play an even greater role in engineering innovation, driving the next generation of optimized, high-performance systems. The synergy between AI, high-performance computing, and surrogate modeling holds immense potential for shaping the future of engineering design, making it more efficient, cost-effective, and intelligent.

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