

Article

Modeling of Multi-Machine System by means of Facts Device for Aggregate Transient Stability

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A B S T R A C T

In this paper, transient stability of IEEE 9- bus system collective with Unified Power Flow Controller (UPFC), has been complete UPFC based on Voltage Source Controller (VSC) has a higher switching frequency, an obvious voltage harmonic and a lower voltage level. Further down a symmetrical three-phase short circuit with a diverse fault locations were used and the load angle variation also studied to test the control performance. The multi machine system combined with UPFC controller, perform outstanding to reduce damping oscillation in power system observed in results of simulation.

Keywords: FACTS, UPFC, Transient Stability, Reactive Power Compensation

Introduction

Nowadays, the upsurge in loading of existing power transmission system consequences in the problems of voltage instability. Maintaining constant voltage level at all buses is a major challenge due to heavy loading on transmission network it make the stabilizing problem more thought-provoking. With the application of FACTS devices, the stability of FACTS devices not only increase the power transmission capability, but also enhance the stability, transfer capability, as well as reduce the transmission losses.²

These capabilities make the UPFC greatest power full device in current scenario control and transmission system. To find the best location for UPFC and the angle and quantity voltage to be injected is a major issue. In the current refurbishment energy market, novel modelling styles for UPFC and controller design are being reputable to elevate

the power system enactments.³⁻⁴ UPFC is covered of shunt and series converter which are linked via a common dc link. The series transformer is used to attach the series converter to the transmission line and inject series voltage V_b . Operating function of shunt convertor is to amount active power, which is mandatory by series converter, dc bus voltage regulator to overcome losses in the line and also rewards reactive power independently. It control and meet the varied objects in diversity of conducts. This has made UPFC generalize to control for numerous usages.⁵ The numerous researchers have industrialized few tactic to classify the optimal location in transmission line.⁶ An optimization algorithms have used to get the size and optimal location.⁷ In section II dissertation about UPFC controller and its topology, Section III present modeling and simulation of multi machine system using with and without UPFC and Consequences and deliberations are talked in Section IV.

Unified Power Flow Controller

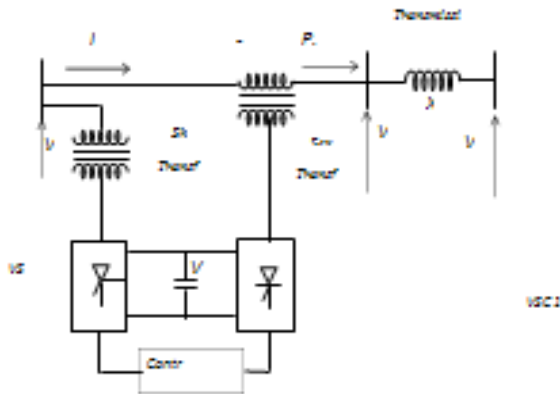


Figure 1. Single-Line Diagram of a UPFC

The UPFC concept was planned by Gyugyi in 1991. It is a powerful FACTS device that uses two voltage source converters together (SVC). Since voltage source converters are used along with passive devices to control flow, UPFC provides fast-acting reactive power compensation on high-voltage electricity transmission networks. UPFC works in both directions to maintain real and reactive power in transmission systems.

The UPFC combines with two FACTS devices: the Static Synchronous Series Compensator (SSSC) and the Static Synchronous Compensator (STATCOM). In the presence of two converters, UPFC supplies active and reactive power. [8] In steady-state operation, UPFC neither injects reactive power nor absorbs active power.

The voltage source converters VSC1 and VSC2 are connected to the transmission line by coupling transformers as shown in Figure 1.

The DC terminals of the converters are coupled to form a system performance [3],[4]. UPFC is comprised of shunt and series converters which are connected via a common DC link. The series transformer is used to connect the series converter to the transmission line and inject series voltage V_b . The operating function of the shunt converter is to supply active power, which is required by the series converter, a DC bus voltage regulator to overcome losses in the line, and also compensate reactive power independently. It controls and meets diverse objectives in various ways.

About UPFC controller and its Topology

Section III presents modeling and simulation of a multi-machine system using with and without UPFC, and results and discussions are discussed in Section IV.

UPFC provides fast-acting reactive power compensation on high-voltage electricity transmission networks. UPFC works in both directions to maintain real and reactive power in transmission systems.

The active power is exchanged with the help of a DC circuit in UPFC. The reactive power supply in the transmission line and the flow of active power in the transmission line are controlled by controlling the magnitude and supplied angles of voltage by the converters. It is an ability to control line impedance, voltage, and phase angle concurrently or selectively; this capability is due to both shunt and series compensation. UPFC can be used to independently and simultaneously control the flow of active power through the line.

Modelling & Simulation of MMIB Using UPFC

In this section, controlling and simulation of UPFC has been discussed using the MATLAB environment. For a multi-machine (3 machines, 9 bus) system simulation work, the remaining approved out. By seeing the incidence of a three-phase fault and varying diverse system constraints, it has been examined for various answers in this case. With the damping constant, fault clearing time, and the location of fault and its effect on the system stability, learning about the variation of load angle has been carried out during investigation.

WSCC-Multi-Machine Infinite Bus (MMIB) System

The WSCC (Western System Coordinated Council) system having 3-machines, 9-bus with standard values of parameters has been considered as a test case. Figure 2 shows the WSCC 3-machines, 9-bus system.

UPFC controller

UPFC is limited to shunt and series converters which are connected via a common DC link. The adaptable phase angle, voltage, and magnitude can be produced by a series converter.

The primary requirement of real power on condition that by shunt converter but VAR compensator, it can also act as a self-governing operator. The exchange of active power in the UPFC controller is done by the DC link with the loss in the controller component and the flow through the link, which disturbs the DC voltage level.

Hence, a DC voltage regulator is required for the proper operation of the controller, which can be attained by a separate control loop. Finally, a control procedure is required to start up the UPFC.

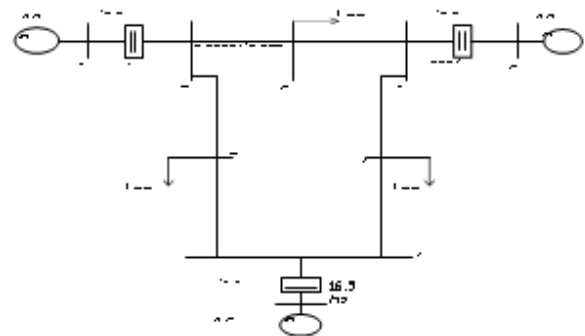


Figure 2. WSCC 3-Machines, 9-Bus System

MATLAB/Simulink based model of WSCC without UPFC

The MATLAB/Simulink grounded model of WSCC 3-Machine 9-Bus system deprived of UPFC shown in Figure 3. In this classical three phase fault and compensating device is not associated. It offers transient response of system in the condition of without fault

MATLAB/Simulink based model of WSCC with UPFC

In MATLAB/Simulink based model of WSCC 3-Machine 9-Bus system with UPFC and three phase fault at three diverse location are shown in Figure 4.

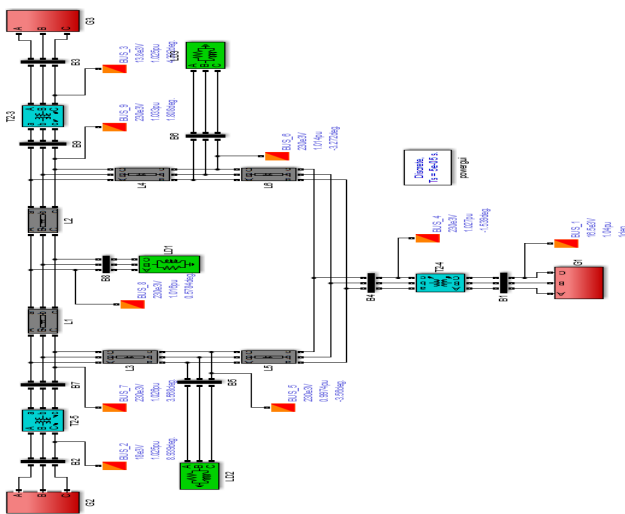


Figure 3. MATLAB/Simulink Based Model of WSCC without UPFC

Converter Controller

In converter controller diverse type of blocks are used like Phase Locked Loop (PLL), measurement, current regulator and reference computation block. To match the frequency of an input signal voltage driven oscillator that repeatedly adjusted by the PLL block. The value of P, Q, Vd, Vq, Id, and Iq are measure by measurement system with the help of bus terminal frequency and voltage. Measurement of Id and Iq reference values done by reference computation block with the help of reference values of P, Q and Vd, Vq. The Vd, Vq value and the current value are generated by current regulator block between both converters and generate sigma signal voltage is compared with DC voltage transferred in Sigma Computation block. To control the operation of converters Firing pulse generator produces firing pulse on basis of reference values. MATLAB/Simulink mode of UPFC is shown in Figure 5.

Result and Discussions

A fault was considered at three diverse locations and their effect was studied with and without UPFC. The three phase fault is occurring just after 5 second and fault clearing time

is 1 second. The variation of relative angular position load angle 1-2, load angle 2-3 and load angle 3-1 with respect to time is observed.

Veriatio of Relative load Angles at Location 1

The results of variation in maximum value of overshoot (degree), steady state stable value of relative angular position(degree) and value of time taken to attain stability (second) at location 1 are shown in Figure 6-8 for with and without UPFC.

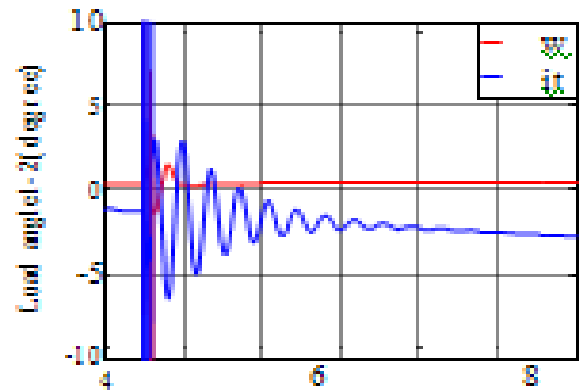


Figure 6. Relative Load Angle 1-2 w.r.t Time

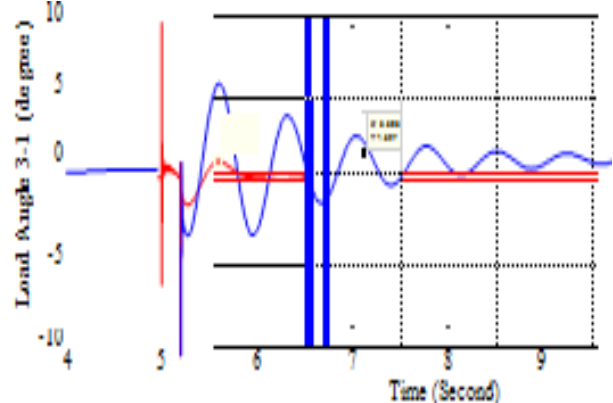


Figure 7. Relative Load Angle 2-3 w.r.t Time

Variation of relative load angles at location 2

The consequences of variation in maximum value of overshoot (degree), steady state stable value of virtual angular position (degree) and value of time occupied to achieve stability (second) at location 1 are shown in Figure 12-14 for with and without UPFC.

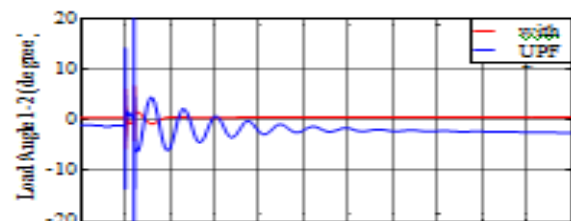


Figure 12. Relative Load Angle 1-2 w.r.t Time

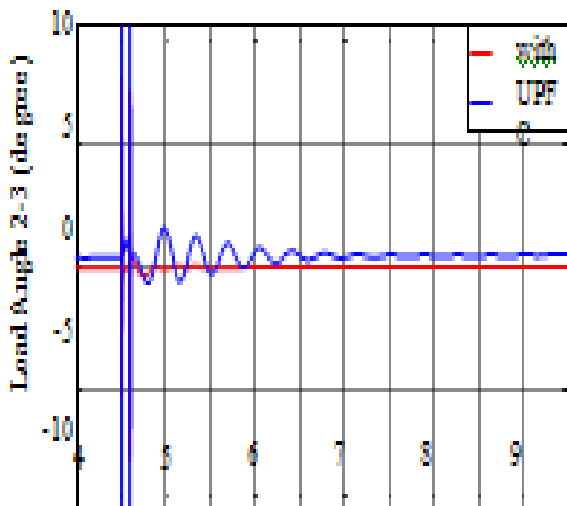


Figure 13. Relative Load Angle 2-3 w.r.t Time

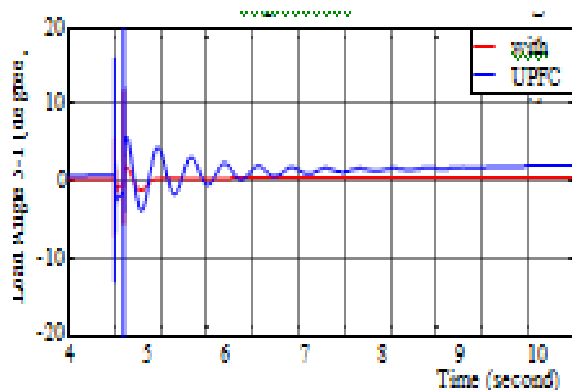


Figure 14. Relative Load Angle 3-1 w.r.t Time

It can be experiential from above figures that regardless of location of fault, UPFC decreases the time taken to attain stability value approximate 1/4rd of uncompensated network. UPFC inclines to the steady state stable value of relative angular position near to zero. Maximum value of overshoot value is abridged by around 1/3rd of uncompensated network by UPFC, regardless of fault location. The response of the generator adjoining to the fault location having more transient.

Conclusions

The current work shows that regardless of the location of fault, 3- Machine 9- Bus WSCC system has been positively modelled and examined by applying voltage source converter type FACTS – UPFC in MATLAB/Simulink environment and the controller presentation in attractive power system transient stability was studied. Imitation result is quite encouraging and shows the effectiveness of UPFC. It has been found to be versatile FACTS controller as it has unique capability of controlling instantaneously/ selectively all the parameters moving power flow in transmission line i.e voltage, impedance and phase angle. It is also seen UPFC can self-sufficiently control both real and reactive power flow

in transmission line. Presentation assessment in terms of transient stability improvement has been deliberate and the load angle variations with time have been plotted in both the cases by varying the location of fault UPFC improves the transient response of system. The extent of change in the value of strictures such as steady state stable value, time taken to accomplish steadiness and maximum value of overshoot, depends on reserve amid fault location and both, generator and Controller.

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